
Randomized load balancing under Loosely correlated state information In fog commuting



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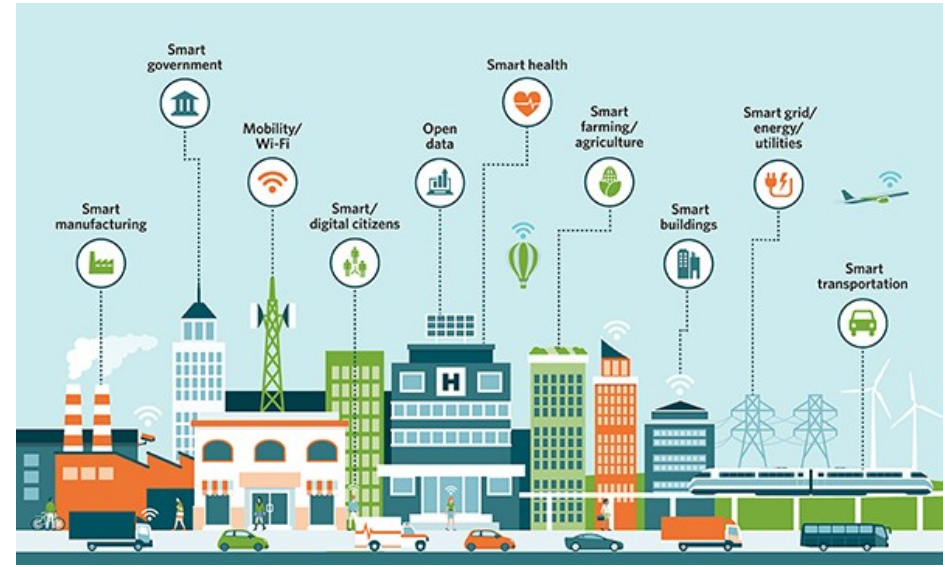
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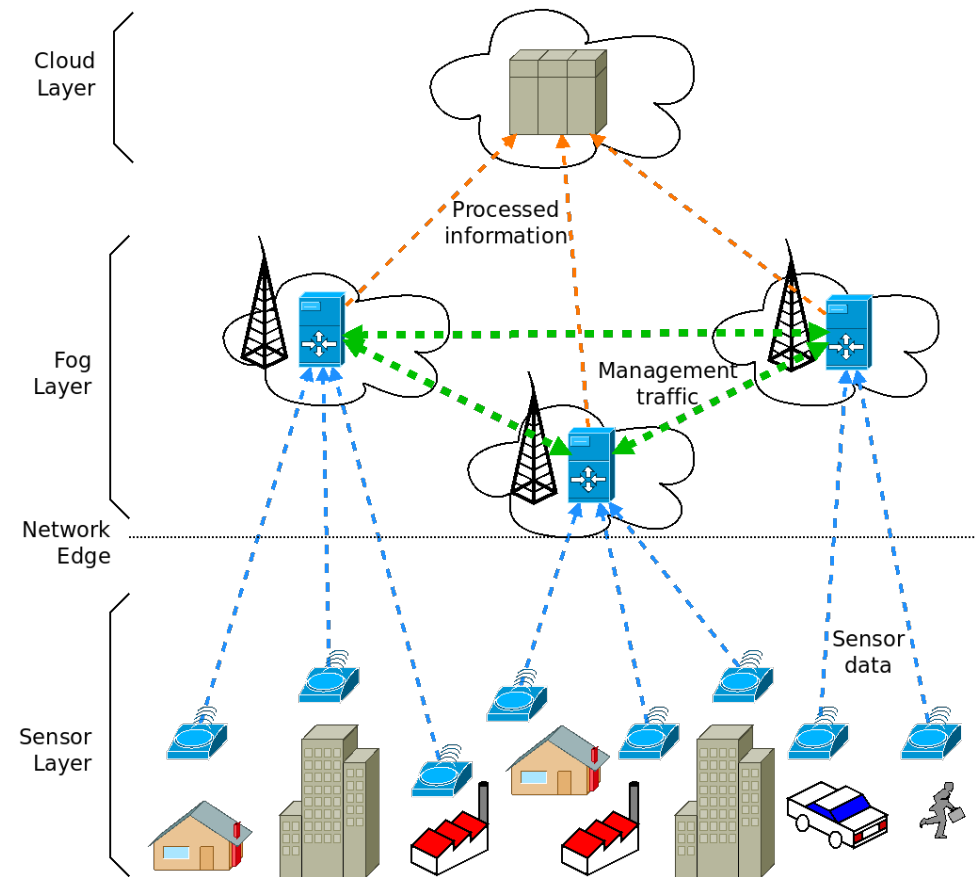
Motivation for Fog computing

- New **paradigm**: Smart cities, large scale sensing applications
- Several fields of application:
 - Urban applications
 - Industrial
 - Automotive
 - Healthcare
 - ...
- New **scenarios**: Cyber-physical systems
 - Geographically distributed sensors
 - Huge amount of data produced
 - Data processing (aggregation, filtering, ...) **close** to sensors



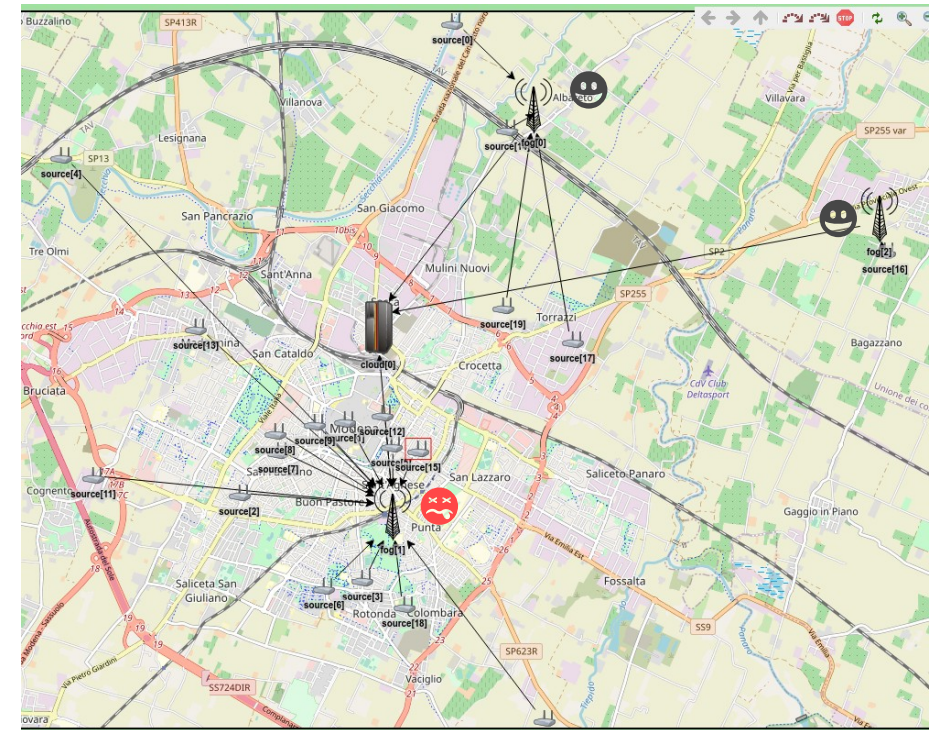
Fog architecture overview

- **Sensors**: data production
- **Fog**: data processing
 - Aggregation, filtering
 - Latency-critical tasks
- **Cloud**: complex applications
- Performance factors:
 - **Network delay**
 - **Processing time @ fog node**
- Addressing delay: optimize infrastructure topology
- Still need to manage the infrastructure
 - → **Load balancing**

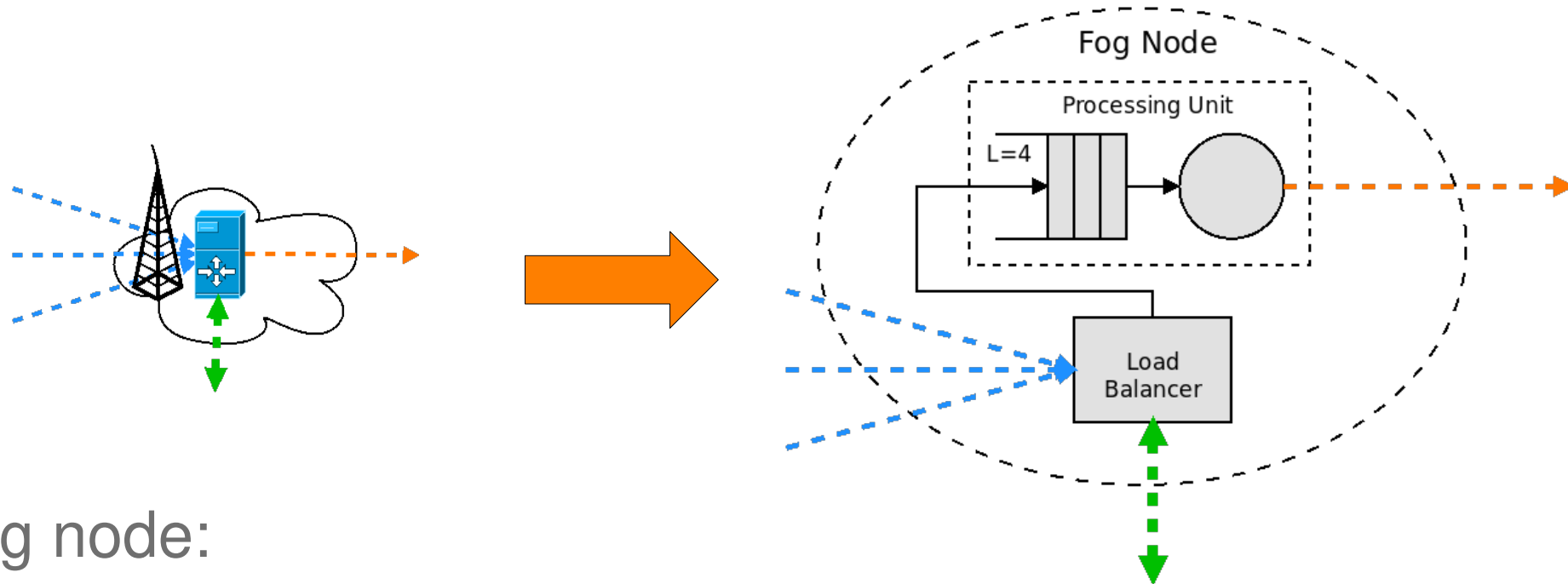


Load balancing in Fog

- Two reasons for load balancing
 - Unbalanced incoming load
 - Transient load fluctuations in the infrastructure
- Forward jobs
 - From overloaded nodes
 - To underloaded nodes
- Requires:
 - Knowledge of local load
 - Interaction with other nodes



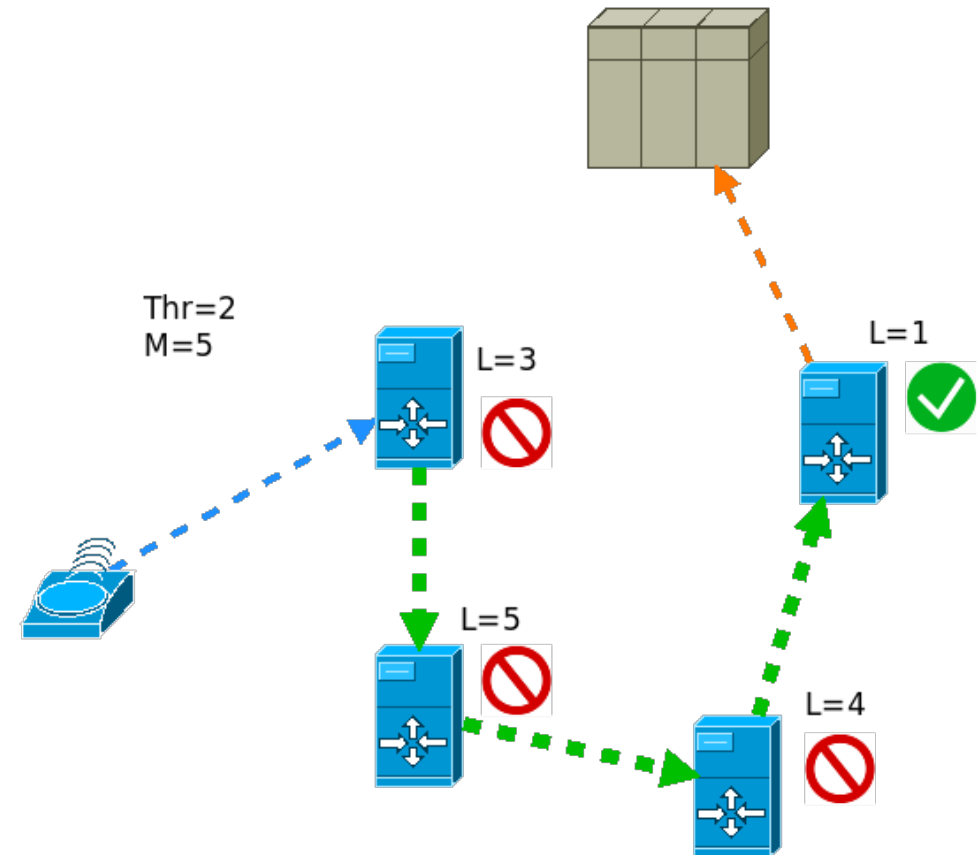
Detail of a fog node



- Fog node:
 - **Load balancer** (LB – implements balancing algorithm)
 - **Processing unit** (PU – server with queue)
- **Load**: jobs in processing unit
- **Finite queue** size: PU can drop jobs

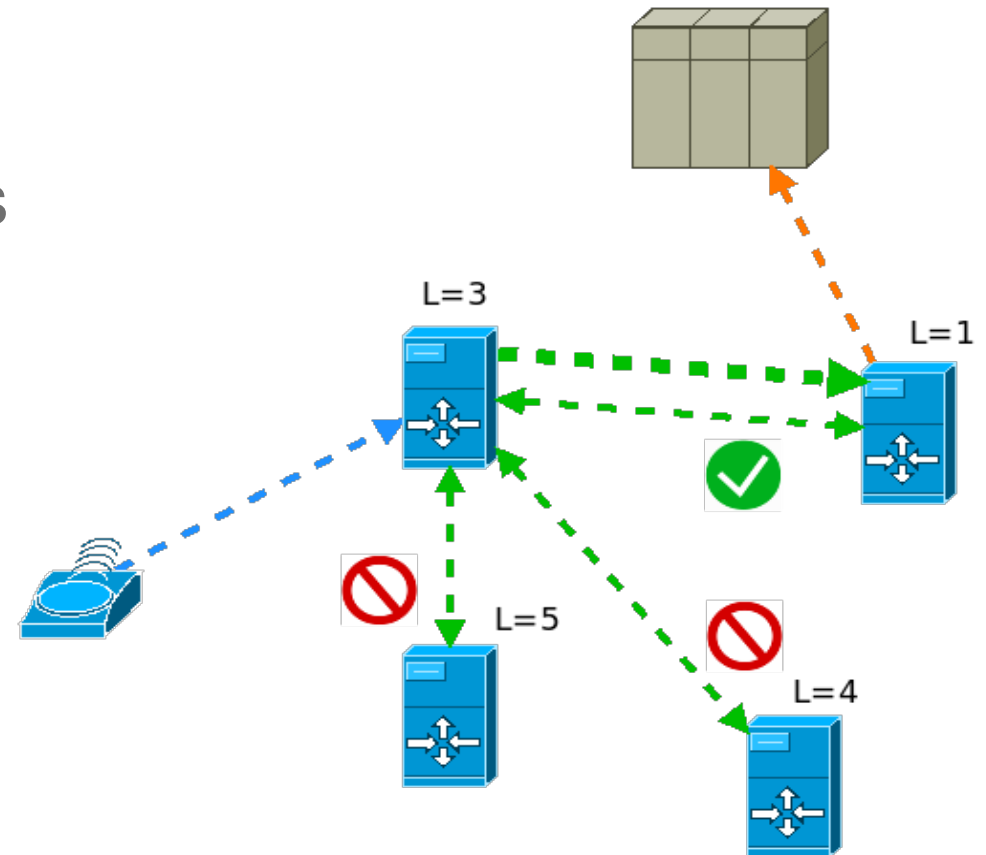
Load-blind approach

- Limited knowledge of load
 - Local load: OK
 - **Remote load: NO**
- Algorithm:
 - Use of **threshold** to determine load overload
 - If overloaded randomly **forwards** to neighbor
 - Up to **M hops**
- Potentially **inefficient**
- Extremely **fast and simple**
- Needs parameter tuning (Thr)



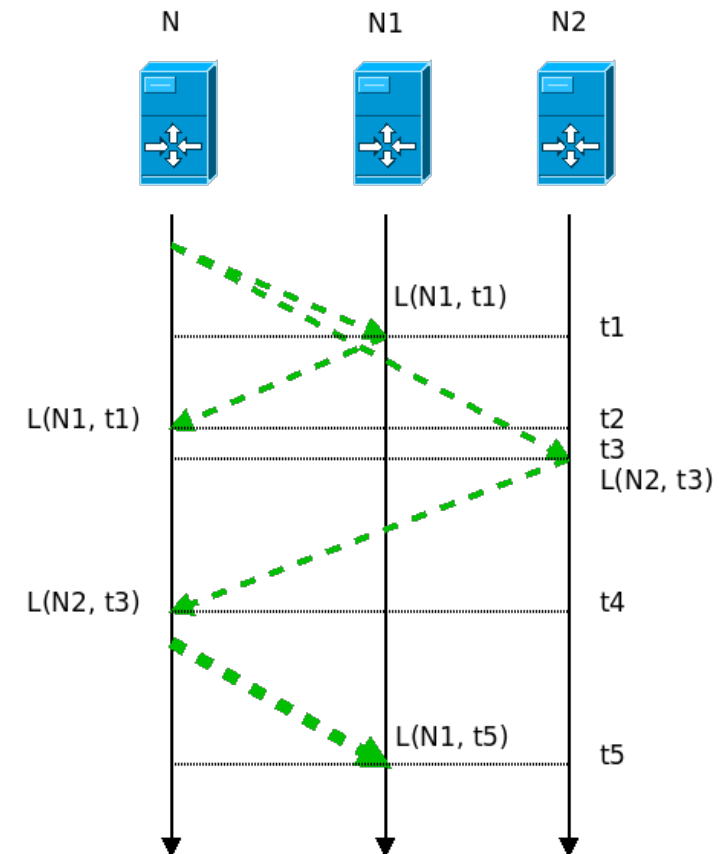
Load-aware approach

- Knows of **local and remote** load
- Algorithm:
 - If **local overload**
 - **Probe** load from neighbors
 - Query message
 - Response message
 - Select **least loaded**
 - Forwards to selected neighbor (or process locally)
- Potentially **more efficient**
- **Risk from inaccurate info**



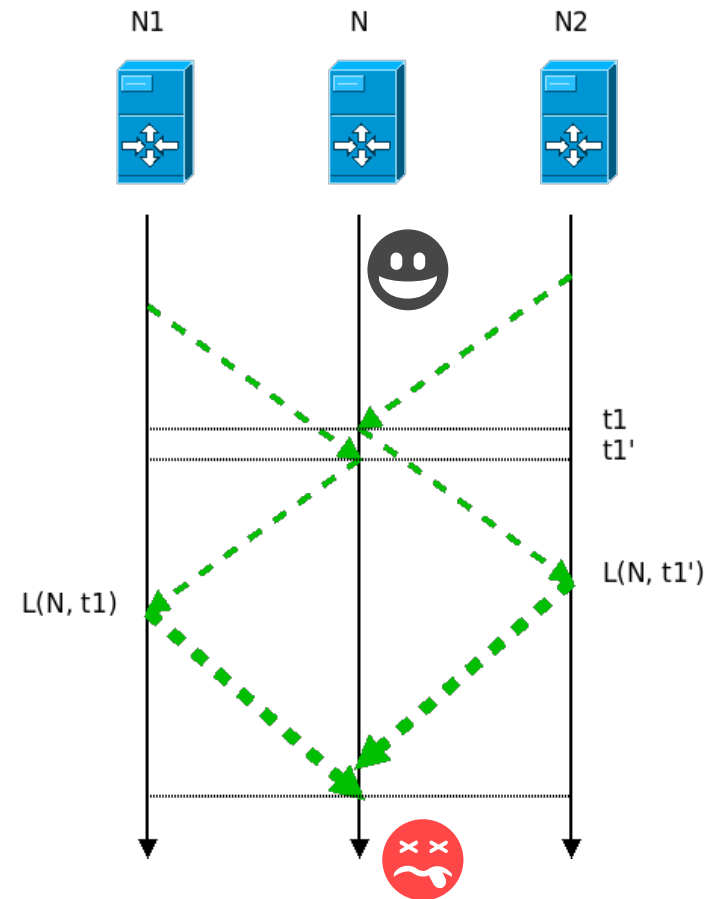
Stale load information

- Stale load:
 - @t2 we know $L(N1, t1)$
 - @t4 we know $L(N2, t3)$
 - we select N1 based on **stale load** information
 - @t5 $L(N1, t5) \neq L(N1, t1)$
- **Load changes over time**
- **Communication delay grows**
 - **Inaccurate information**
 - **Probing less useful**



Herding effect

- Two neighbors probe node N
 - N is **underloaded**
 - All neighbors select N
 - N \rightarrow **overload**
- **Delay in information propagation**
 - Effect of stale load
 - Can cause oscillations
 - Occurs when a node receives multiple concurrent probes

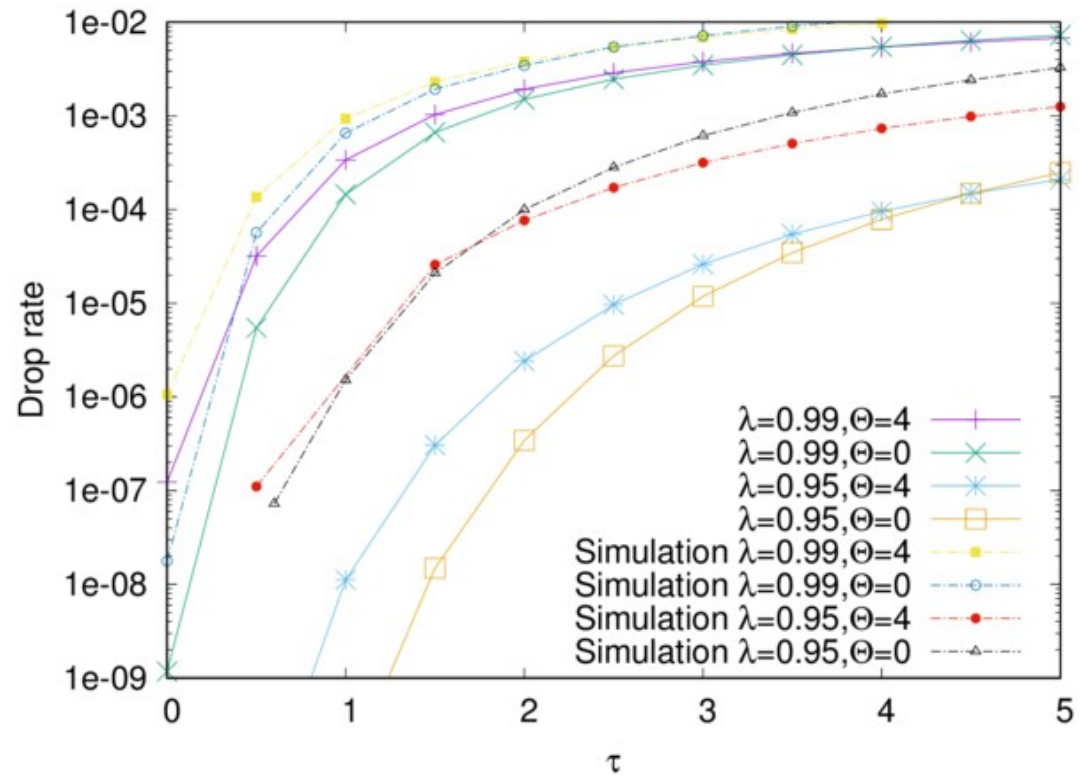


Stale information model

- Queuing model
 - Processing unit
 - Message queue for data exchange among nodes
- Model **loss of correlation** between:
 - Actual load
 - Advertised load
- Perfect correlation → ideal case
- Complete loss of correlation → random load information
- Correlation depends on:
 - **Network delay**
 - **Network load** (affects delay)
 - **Load evolution dynamic**

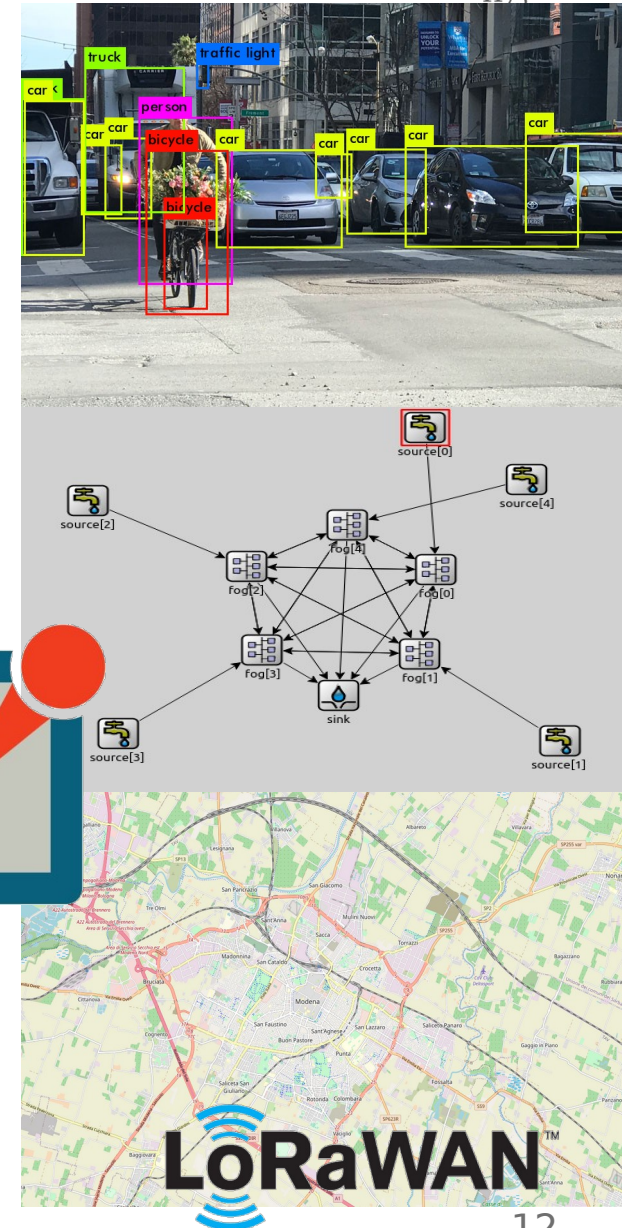
Numerical results

- Drop rate vs. Delay
- Scenario
 - Incoming load
 - Threshold
- Delay grows:
 - Increase of drop rate
- Effects of scenario
 - High load \rightarrow faster degradation
 - High threshold \rightarrow more aggressive probing
 - Detrimental effect for high delay



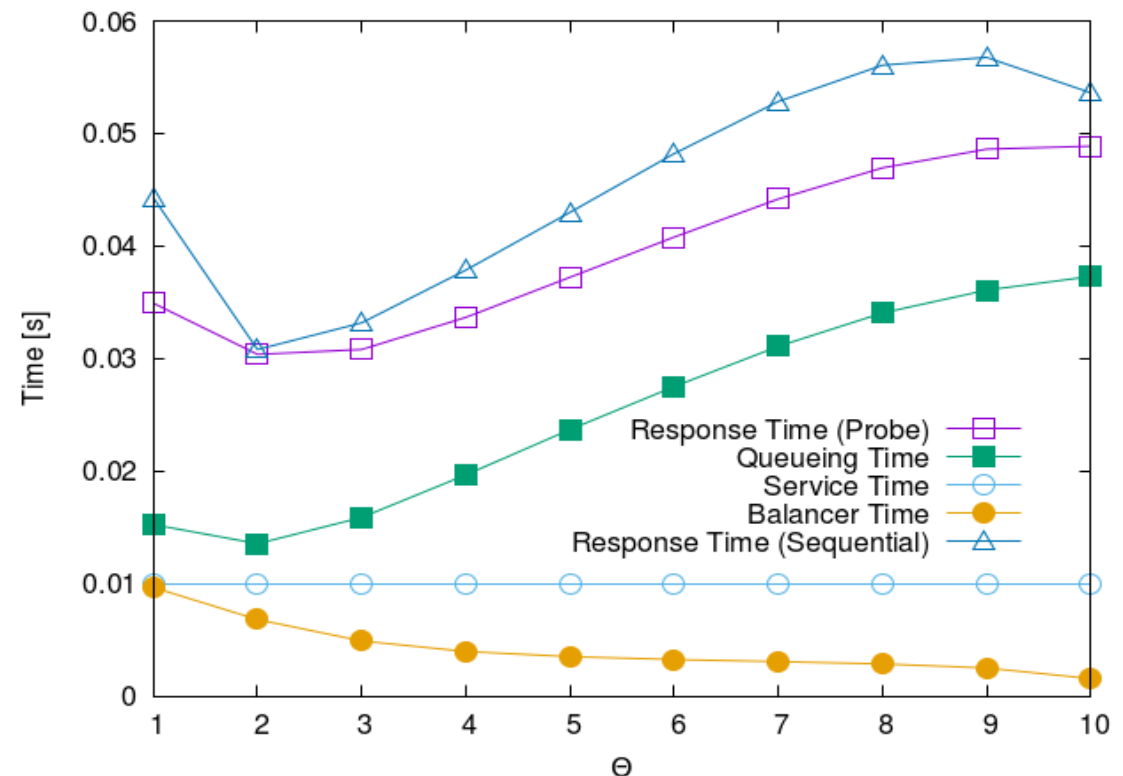
Simulation setup

- Traffic monitoring application, OMNET++ sim
 - Processing images from camera
 - **Object identification** (cars/humans/bikes)
 - Limited queue (K=10, RT application)
 - Proc. time \approx Network delay (10 ms)
- Two scenarios:
 - **Uniform mesh**
 - **Same load** for fog nodes
 - **Same BW** in communication
 - **Geographic** scenario (Modena)
 - Highly variable load
 - Based on **real topography**
 - $BW \propto 1/\text{distance}$ (LoRaWAN)

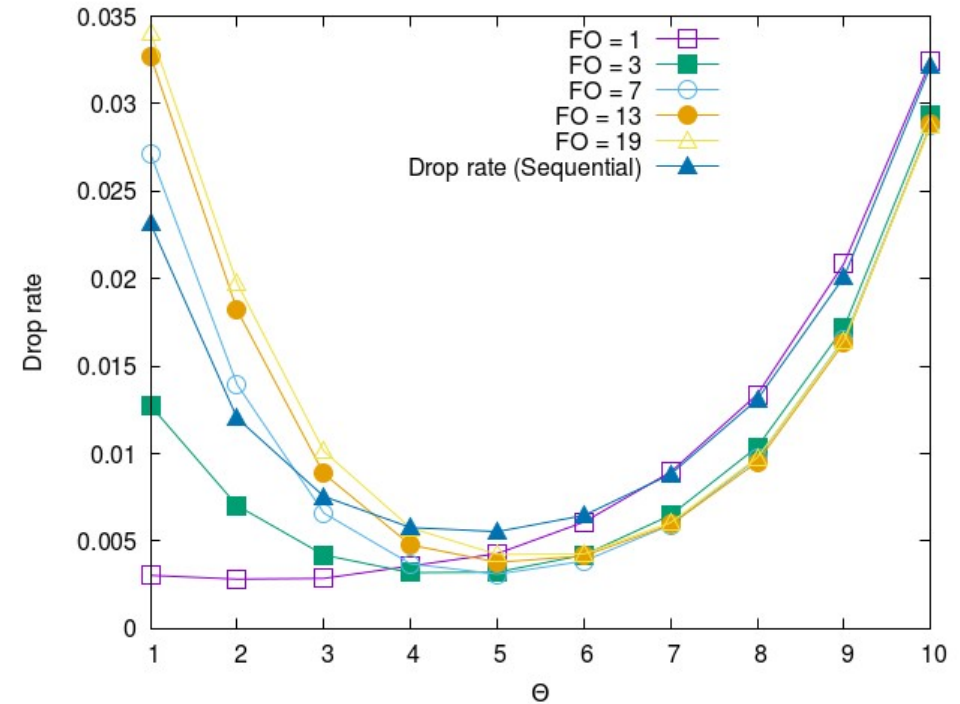
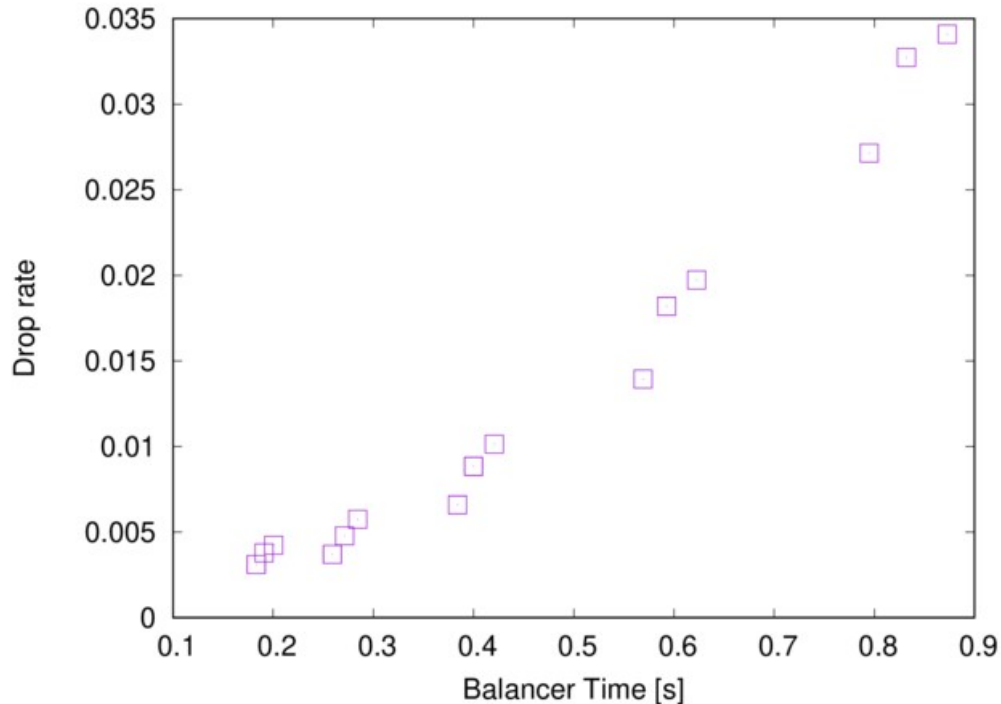


Simulation results

- Mesh scenario
 - Times vs. Threshold Θ
- **Queuing** time
 - Increases with Θ
 - Less balancing
→ longer queues
- **Balancer** time
 - Decreases with time
 - Less invocations
 - Less network load
- **Response** time
 - Sweet point for $\Theta=2$
 - **Probe faster** (and more **stable**) than **Sequential**

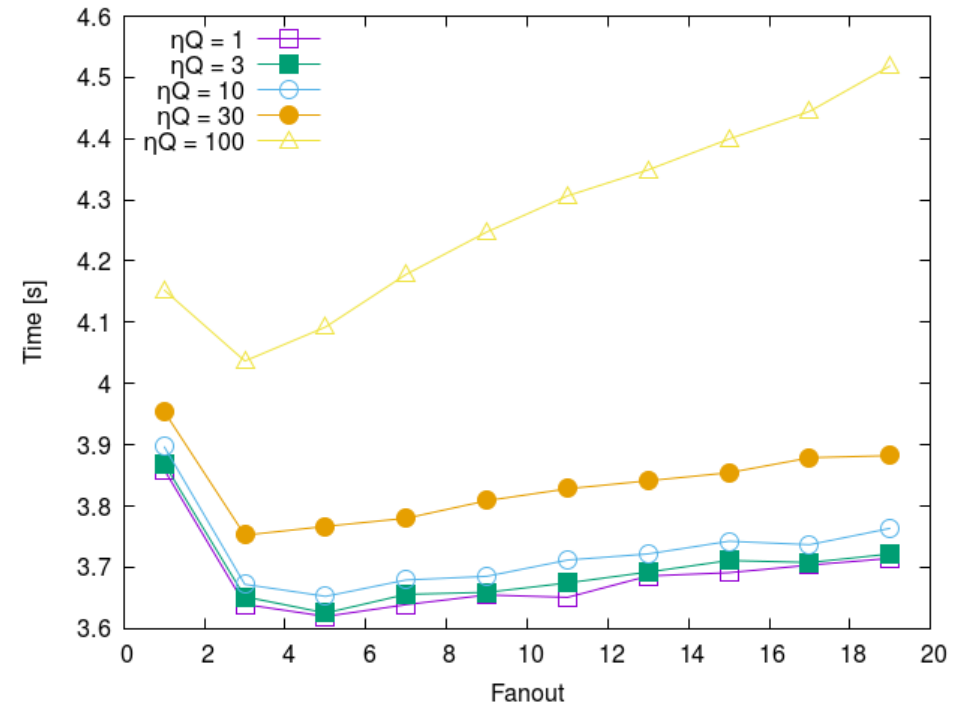
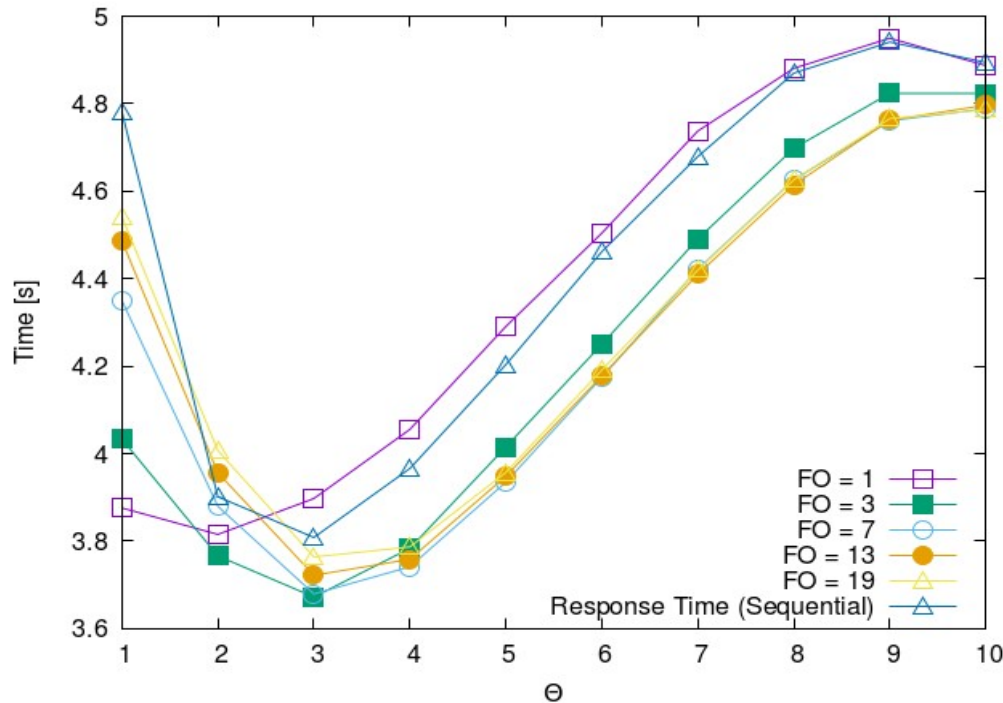


Mesh scenario



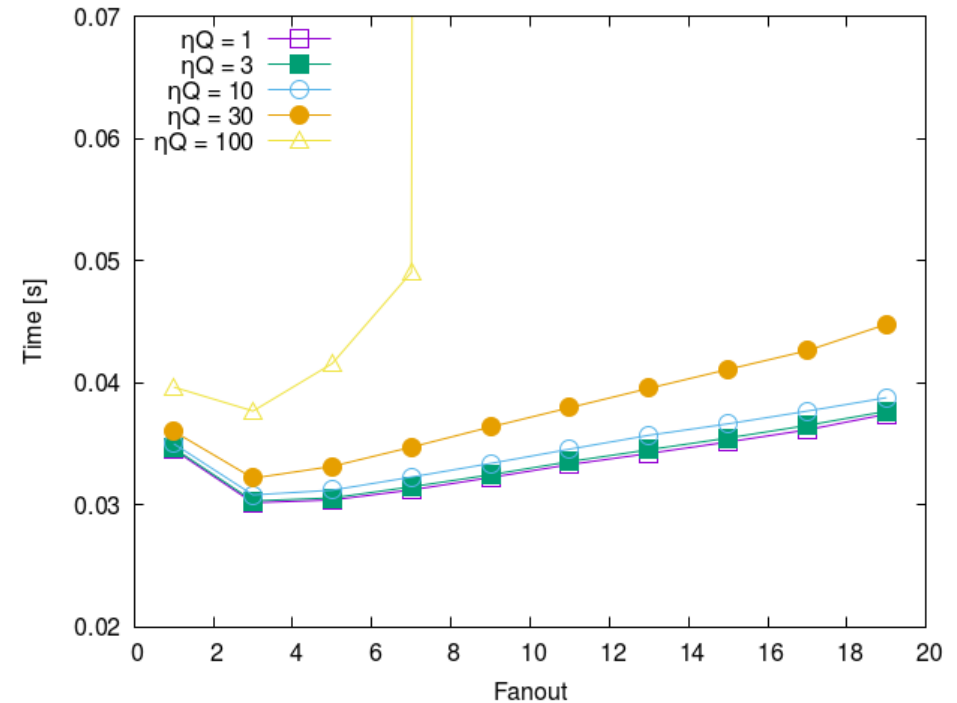
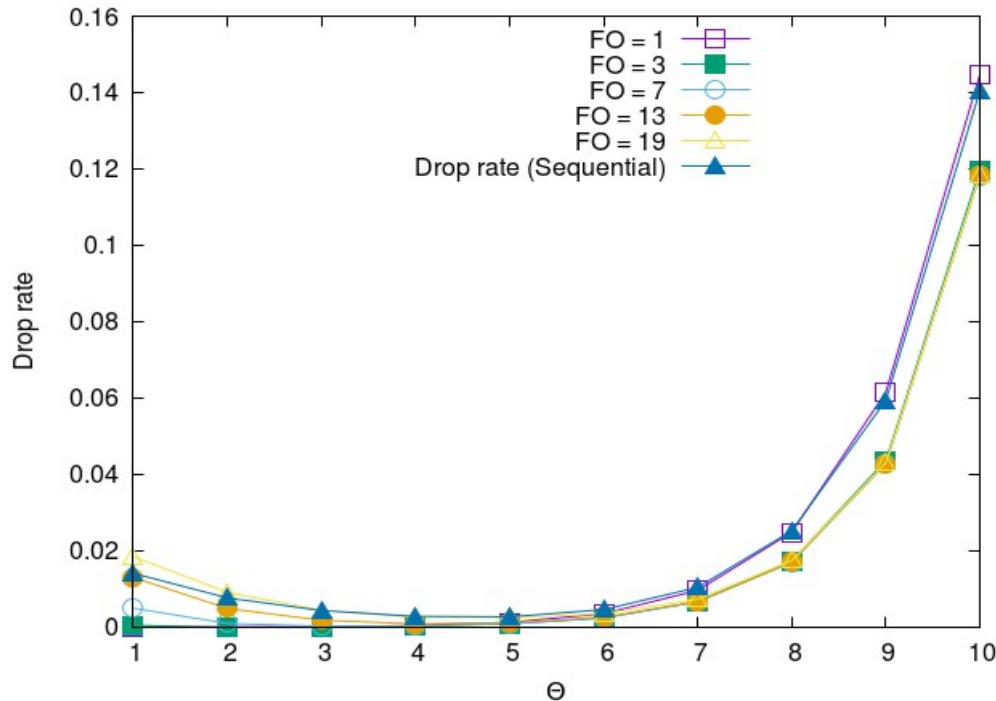
- Strong **correlation** Drop rate / Probe delay (Balancer time)
- **Cup shaped** curve of drop rate vs. θ
- Herding effect:
 - High Fan out, many queries \rightarrow Like load-blind (or worse!)
 - Low fan out reduces this effect

Mesh scenario



- Analysis for different **Fan-Out**
 - FO grows \rightarrow impact of higher drop rate (**apparently** faster)
- **Impact of η_Q** (rate between probe and job size)
 - Large probe messages \rightarrow high delay
 - High Fan-Out \rightarrow high delay

Geographic scenario



- **High variance** of incoming load in fog nodes
 - **Reduced** impact of **herding** effect
 - Only **few nodes** start **probes**
- Risk of **network saturation** in these nodes
 - Evident when probe message is large

Conclusions

- Challenges of Fog computing
 - **Load balancing** in a distributed infrastructure
 - Impact of **communication overhead**
- Contributions
 - **Probe-based** load balancing algorithm
 - **Mathematical model** of delay effects
- Experimental evaluation
 - **Numerical analysis** on mathematical model
 - **Simulation** (several parameters and a realistic scenario)
- Open issues
 - Validations with **prototypes**
 - **Proactive probing** (informed protocols)

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